

**COMMANDER SK SIZE A (0.25 to 0.75 kW)**  
**ELECTROMAGNETIC COMPATIBILITY DATA**

**PRODUCT** SKA1200025 – SKA1200075

**General note on EMC data**

The information given in this data sheet is derived from tests and calculations on sample products. It is provided to assist in the correct application of the product, and is believed to correctly reflect the behaviour of the product when operated in accordance with the instructions. The provision of this data does not form part of any contract or undertaking. Where a statement of conformity is made with a specific standard, the company takes all reasonable measures to ensure that its products are in conformance. Where specific values are given these are subject to normal engineering variations between samples of the same product. They may also be affected by the operating environment and details of the installation arrangement.

**Note on EN 61800-3 and IEC 61800-3**

The data refers to EN 61800-3:1997 including amendment A11, which is the version applicable under the EMC Directive at the time of writing, and the associated standard IEC 61800-3:1996. This will be replaced by the CENELEC version of IEC 61800-3:2004 at a date not currently known.

**IMMUNITY**

The drive complies with the following international and European harmonised standards for immunity:

Standard	Type of immunity	Test specification	Application	Level
EN 61000-4-2 IEC 61000-4-2	Electrostatic discharge	6kV contact discharge 8kV air discharge	Module enclosure	Level 3 (industrial)
EN 61000-4-3 IEC 61000-4-3	Radio frequency radiated field	10V/m prior to modulation 80 - 1000MHz 80% AM (1kHz) modulation	Module enclosure	Level 3 (industrial)
EN 61000-4-4 IEC 61000-4-4	Fast transient burst	5/50ns 2kV transient at 5kHz repetition frequency via coupling clamp	Control lines	Level 4 (industrial harsh)
		5/50ns 2kV transient at 5kHz repetition frequency by direct injection	Power lines	Level 3 (industrial)
EN 61000-4-5 IEC 61000-4-5	Surges	Common mode 4kV 1.2/50µs waveshape	AC supply lines: line to earth	Level 4
		Differential mode 2kV	AC supply lines: line to line	Level 3
		Common mode 1kV	Control lines <sup>1</sup>	
EN 61000-4-6 IEC 61000-4-6	Conducted radio frequency	10V prior to modulation 0.15 - 80MHz 80% AM (1kHz) modulation	Control and power lines	Level 3 (industrial)
EN 61000-4-11 IEC 61000-4-11	Voltage dips, short interruptions & variations	All durations	AC supply lines	
EN 61000-6-1 IEC 61000-6-1	Generic immunity standard for the residential, commercial and light - industrial environment			Complies
EN 61000-6-2 <sup>2</sup> IEC 61000-6-2	Generic immunity standard for the industrial environment			Complies
EN 61800-3 IEC 61800-3	Product standard for adjustable speed power drive systems (immunity requirements)		Meets immunity requirements for first and second environments	

<sup>1</sup> Applies to ports where connections may exceed 30m length. Special provisions may be required in some cases – see additional information below.

<sup>2</sup> Supersedes EN 50082-2

Unless stated otherwise, immunity is achieved without any additional measures such as filters or suppressors. To ensure correct operation the wiring guidelines specified in the User Guide must be carefully adhered to. All inductive components such as relays, contactors, electromagnetic brakes etc. associated with the drive must be fitted with appropriate suppression, otherwise the immunity capability of

the drive may be exceeded.

## EMISSION

Emission occurs over a wide range of frequencies. The effects are divided into three main categories:

- Low frequency effects, such as supply harmonics and notching.
- High frequency emission below 30MHz where emission is predominantly by conduction.
- High frequency emission above 30MHz where emission is predominantly by radiation.

## SUPPLY VOLTAGE NOTCHING

Because of the use of uncontrolled input rectifiers the drives cause no significant notching of the supply voltage.

## SUPPLY HARMONICS

The input current contains harmonics of the supply frequency. Since the drive input has a low impedance, the harmonic current levels are affected to some extent by the supply impedance (fault current level). The table shows the levels calculated for a fault level of 5kA. This meets and exceeds the requirement of IEC 61800-3 (fault current 250 times the drive rating) and represents a realistic but severe case. A standard Eff2 motor is assumed.

The levels of even harmonics are negligible.

The calculations have been verified by laboratory measurements on sample drives. Note that the r.m.s. current in these tables may be lower than that specified in the published technical data, since the latter is a worst-case value provided for safety reasons which allows for supplies with high fault levels and less efficient motors.

The supply voltage for the calculation was 230V 50Hz but the harmonic percentages do not change substantially for other voltages and frequencies within the drive specification.

Drive (kW)	r.m.s. current (A)	Fund current (r.m.s.)	THD (%) <sup>*</sup>	Harmonic order, magnitude as % fundamental											
				3	5	7	9	11	13	15	17	19	21	23	25
1200025 (0.25)	3.68	1.61	205.6	96.8	90.9	82.6	72.8	62.1	51.3	41.2	32.3	24.9	19.0	14.5	11.1
1200037 (0.37)	5.04	2.28	196.9	96.3	89.4	79.9	68.8	57.2	46.0	35.9	27.4	20.6	15.3	11.3	8.2
1200055 (0.55)	7.65	3.49	194.7	96.7	90.3	81.4	70.5	58.6	46.3	34.4	23.7	14.5	7.3	2.6	2.6
1200075 (0.75)	10.10	4.78	186.3	96.2	88.9	78.7	66.6	53.5	40.4	28.2	17.6	9.1	3.1	2.2	3.9

\* Total Harmonic Distortion, expressed as percentage of fundamental

To give some indication of how the currents vary with source impedance, and to allow a realistic assessment of operation on a “weak” supply, the following table shows the levels for a low-current supply of residential type, as specified in IEC 60725<sup>1</sup>. Note that harmonic currents from order 9 upwards are considerably reduced.

Drive (kW)	r.m.s. current (A)	Fund current (r.m.s.)	THD (%) <sup>*</sup>	Harmonic order, magnitude as % fundamental											
				3	5	7	9	11	13	15	17	19	21	23	25
1200025 (0.25)	3.05	1.61	160.9	94.1	83.1	68.4	51.8	35.2	20.4	9.1	4.5	6.7	7.7	6.6	4.2
1200037 (0.37)	4.13	2.28	151.1	92.9	80.0	63.1	44.6	27.1	12.8	4.3	6.0	7.5	6.4	3.8	1.3
1200055 (0.55)	5.97	3.46	140.5	91.6	76.5	57.2	37.0	18.9	5.1	3.6	7.0	6.5	3.7	0.6	1.9
1200075 (0.75)	7.86	4.73	132.9	90.2	72.6	51.0	29.5	11.6	0.7	6.2	6.8	4.2	0.7	1.9	2.9

## Input line inductors (line chokes)

Where necessary, a reduction in harmonic current levels can be obtained by fitting inductors in the input supply lines to the drive. This also gives increased immunity from supply disturbances such as voltage surges caused by the switching of high-current loads or power-factor correction capacitors on the same supply circuit. The following table shows the corresponding harmonics where inductors of approximately 2% per unit are fitted in the supply lines. Higher inductor values should be applied with caution because of the reduction in output voltage. Line inductors should be rated for continuous operation at the RMS current shown, and for a peak current (for no magnetic saturation) of at least twice that.

<sup>1</sup>  $Z = 0.4 + j0.25 \Omega$

Drive (kW)	L (mH)	RMS current	Fund current (rms)	THD (%)*	Harmonic order, magnitude as % fundamental											
					3	5	7	9	11	13	15	17	19	21	23	25
1200025 (0.25)	2.25	2.65	1.62	130.1	89.7	71.5	49.6	28.7	12.8	6.1	6.7	5.9	3.8	2.6	2.7	2.5
1200037 (0.37)	2.25	3.62	2.29	122.4	87.8	66.9	42.9	21.6	8.1	6.4	6.5	4.4	2.7	2.7	2.5	1.7
1200055 (0.55)	1	5.73	3.49	130.0	89.6	71.4	49.5	28.5	12.5	5.8	6.5	5.8	3.7	2.5	2.7	2.4
1200075 (0.75)	1	7.53	4.77	122.3	88.0	67.3	43.4	22.0	8.2	6.1	6.4	4.4	2.6	2.7	2.5	1.7

Suitable chokes are available from Control Techniques with the following part numbers:

2.25mH           4402-0224  
1mH               4402-0225

### The effect of load on harmonics

With reducing load the major harmonics fall in absolute magnitude, although they generally rise as a fraction of the fundamental. Note that it is load power which controls input current, i.e. the product of torque and speed.

### Harmonic emission standards IEC 61000-3-2, EN 61000-3-2

When applied to equipment for professional use these standards set harmonic limits for ratings below 1kW input power. This applies to the size A Commander SK range except for the 0.75kW rating, where input power exceeds 1kW at full load because typical motor efficiency is 70%.

Larger line chokes than shown above are required in order to conform to this standard. Chokes are available from Control Techniques with the following part numbers:

Drive (kW)	L (mH)	Current rating (A)	Choke part number
1200025 (0.25)	4.5	2.4	4400-0239
1200037 (0.37)	9.75	3.2	4400-0238
1200055 (0.55)	16.25	4.5	4400-0237

The choke current ratings are considerably lower than the drive nominal input current ratings because of the improved power factor of the drive when using the choke.

The chokes cause some reduction in the voltage supplied to the drive. This tends to reduce the available torque at maximum speed. The drive uses slip compensation to maintain the torque, resulting in some increase in motor current. For a standard 4-pole motor with the 0.25kW and 0.37kW drives the current remains within the motor rating, so there is no loss of specified performance. With the 0.55kW drives a reduction in full-speed torque of 18% occurs. If this is unacceptable then the 0.75kW drive should be used. For other motors, a test should be carried out to ensure that sufficient full-speed torque is available.

System designers should consider carefully whether conformance to these standards is really a requirement for their application. It is the total input power of the system or machine which must be less than 1kW for these standards to apply. This is unusual in professional machinery.

### Further measures for reducing harmonics

It is unusual for harmonics to pose a problem unless a substantial part (e.g. over 50%) of the supply system capacity is accounted for by drives or other power electronic loads. Harmonic currents from drives add approximately arithmetically. It is usually most cost-effective to analyse a complete installation for harmonic current or voltage and to apply remedial measures such as harmonic filters, if necessary, for the entire installation at the common supply point.

### Voltage fluctuations and flicker

When running at constant load the drive does not generate voltage fluctuations or flicker. Care must be taken to ensure that the application does not cause the load to vary rapidly, resulting in flicker. Cyclical variations in the region of 2Hz to 20Hz are likely to cause irritating lighting flicker and should be avoided. When power is first applied the drive draws an inrush current which is limited to 13.2A r.m.s., this meets the requirements of EN 61000-3-3.

## CONDUCTED EMISSION

Radio frequency emission in the frequency range from 150kHz to 30MHz is generated by the switching action of the main power devices (IGBTs) and is mainly conducted out of the equipment through electrical wiring. It is essential for compliance with the emission standards that the recommended filter and a shielded (screened) motor cable are used. Most types of cable can be used provided it has an overall screen, for example the screen formed by the armouring of steel wired armoured cable is acceptable. The capacitance of the cable forms a load on the drive and should be kept to a minimum. Compliance tests were done with cable having a capacitance between the three power cores and the screen of 412pF per metre (measured at 1kHz), which is typical of steel wire armoured cable. In addition to motor cable length, conducted emission will also vary with drive switching frequency: selecting the lowest switching frequency will produce the lowest level of emission. Wiring guidelines are given in Figure 1 which shows full precautions where minimum emissions are required.

The drive contains a cost-effective internal input filter which gives a reduction of about 30dB in the level of emission at the supply terminals. Unlike a conventional filter, the internal filter continues to provide this attenuation with a long motor cable. For practical purposes, this filter in conjunction with a screened motor cable is sufficient to prevent the drive from causing interference to most good-quality industrial equipment. It is recommended that the filter be used in any situation unless the earth leakage current, which is up to 10mA, is unacceptable. The Getting Started guide gives instructions on how to remove and replace it.

For applications where there are stricter requirements for radio frequency emission, e.g. to the generic standards EN 61000-6-4 etc. or first environment in EN 61800-3, the optional external filter must be used. The drive complies with the requirements for conducted emission in the following standards.

The standard filter has an earth leakage current of 51mA maximum under normal working conditions. It should be used in conjunction with the drive internal filter, giving a total maximum current of 52mA. (The currents do not add arithmetically since they have different frequencies.)

The low-leakage filter has a reduced earth leakage current of 2.5mA maximum, but the permissible motor cable length is reduced. To achieve this earth leakage value, the drive internal filter must be disconnected.

Motor cable length (m)	Filter and switching frequency (kHz)											
	Internal				Standard (4200-6122)				Low Leakage (4200-6123)			
	3	6	12	18	3	6	12	18	3	6	12	18
2	E2U	E2U	E2R	E2R	R	R	R	R	R			
5	E2U	E2U	E2R	E2R	R				R			
10	E2U	E2R	E2R	E2R	R				R			
20	E2R	E2R	E2R	E2R	R							
30	E2R	E2R	E2R	E2R						-	-	-
50	E2R	E2R	E2R	E2R					-	-	-	-
75	E2R	E2R	E2R	E2R				E2U	-	-	-	-
100	E2R	E2R	E2R	E2R		E2U	E2U	E2U	-	-	-	-

### Key to table

The requirements are listed in descending order of severity, so that if a particular requirement is met then all requirements listed after it are also met.

	Standard	Description	Frequency range	Limits	Application
R	EN 61000-6-3 (previously EN 50081-1)	Generic emission standard for the residential commercial and light - industrial environment	0.15 - 0.5MHz	66-56dB $\mu$ V quasi peak 56-46dB $\mu$ V average	AC supply lines
			0.5 - 5MHz	56dB $\mu$ V quasi peak 46dB $\mu$ V average	
			5 - 30MHz	60dB $\mu$ V quasi peak 50dB $\mu$ V average	

	EN 61800-3 IEC 61800-3	Product standard for adjustable speed power drive systems	Requirements for the first environment <sup>1</sup> , with unrestricted distribution		
I	EN 61000-6-4 (previously EN 50081-2)	Generic emission standard for the industrial environment	0.15 - 0.5MHz	79dB $\mu$ V quasi peak 66dB $\mu$ V average	AC supply lines
			0.5 -30MHz	73dB $\mu$ V quasi peak 60dB $\mu$ V average	
	EN 61800-3 IEC 61800-3	Product standard for adjustable speed power drive systems	Requirements for the first environment <sup>1</sup> with restricted distribution <sup>2</sup>		
E2U	EN 61800-3 IEC 61800-3	Product standard for adjustable speed power drive systems	Requirements for the second environment with unrestricted distribution		
E2R	EN 61800-3 IEC 61800-3	Product standard for adjustable speed power drive systems	Requirements for the second environment with restricted distribution <sup>2</sup>		
-	Operation in this condition is not recommended				
<sup>1</sup>	The first environment is one where the low voltage supply network also supplies domestic premises				
<sup>2</sup>	When distribution is restricted, drives are available only to installers with EMC competence				

**- Caution -**

This caution applies where the drive is used in the first environment according to EN 61800-3.  
*This is a product of the restricted distribution class according to IEC 61800-3. In a domestic environment this product may cause radio interference in which case the user may be required to take adequate measures.*

**Notes**

- Where the drive is incorporated into a system with rated input current exceeding 100A, the higher emission limits of EN 61800-3 for the second environment are applicable, and no filter is then required.
- Operation without an external filter is a practical cost-effective possibility in an industrial installation where existing levels of electrical noise are likely to be high, and any electronic equipment in operation has been designed for such an environment. This is in accordance with EN 61800-3 in the second environment, with restricted distribution. There is some risk of disturbance to other equipment, and in this case the user and supplier of the drive system must jointly take responsibility for correcting any problem which occurs.**

**Conducted emission test data**

The conducted emission from a SKA1200075 operating with filter part no. 42000-6122, at 3kHz switching frequency is shown in Figure 4 with 10m of screened motor cable and Figure 5 with 100m.

**Recommended filters**

Drive	Motor cable length (m)	Input filter (CT Part No.)	Filter Type
SKA1200025 – 1200075	1 to 100	4200-6122	Footprint / Bookend Standard
SKA1200025 – 1200075	1 to 30	4200-6123	Footprint / Bookend Low Earth Leakage (<3.5mA)

Mechanical and electrical data, including earth leakage current and power loss, is given in the drive user guide.

**- WARNING -**

Except for the low earth leakage version, these filters have earth leakage current exceeding 3.5mA. A permanent fixed earth connection is necessary to avoid electrical shock hazard. Further precautions, such as a supplementary earth connection or earth monitoring system, may also be required.

**Multiple drives**

In multiple drive applications it is preferable to use one RFI filter for each drive. Filters of appropriate current rating may be shared between drives, but deviations from the stated standards may then occur. The motor cable length limits apply to the total for all drives connected to a given filter.

**Related product standards**

The conducted emission levels specified in EN 61000-6-3 and EN 61000-6-4 are equivalent to the levels required by the following product specific standards:

<b>Conducted emission from 150kHz to 30MHz</b>		
<b>Generic standard</b>	<b>Product standard</b>	
EN 61000-6-3	EN 55011 Class B CISPR 11 Class B	Industrial, scientific and medical equipment
	EN 55014 CISPR 14	Household electrical appliances
	EN 55022 Class B CISPR 22 Class B	Information technology equipment
EN 61000-6-4	EN 55011 Class A Group 1 CISPR 11 Class A Group 1	Industrial, scientific and medical equipment
	EN 55022 Class A CISPR 22 Class A	Information technology equipment

## RADIATED EMISSION

### Industrial emission standard EN 61000-6-4

When installed in a standard metal enclosure according to the wiring guidelines in Figure 1 and using the standard or low-leakage mains input filters filters, (CT part number 4200-6122 or 4200-6123), the drive will meet the radiated emission limits required by the generic industrial emission standard EN 61000-6-4.

### Important note

Compliance was achieved in tests using representative enclosures and following the guidelines given. Every effort was made to ensure that the arrangements were robust enough to be effective despite the normal variations which will occur in practical installations. However no warranty is given that installations built according to these guidelines will necessarily meet the same emission limits.

The limits for emission required by the generic emission standards are summarised in the following table:

Radiated emission from 30 to 1000MHz				
Standard	Application	Frequency range	Limits	Comments
EN 61000-6-4	Enclosure	30 - 230MHz	40dB $\mu$ V/m quasi peak at 10m	Standard specifies limits of 30 and 37dB $\mu$ V/m respectively at a measuring distance of 30m; emission may be measured at 10m if limits are increased by 10dB
		230 - 1000MHz	47dB $\mu$ V/m quasi peak at 10m	

EN 61800-3:1997 requires the following:

As EN 61000-6-3	First environment - unrestricted distribution
As EN 61000-6-4	First environment - restricted distribution - any drive
30 – 230MHz 40dB $\mu$ V/m at 30m 230 – 1000MHz 50dB $\mu$ V/m at 30m	Second environment

### Test Data

The test data is based on radiated emission measurements made on a standard steel enclosure containing a single SKA1200037 drive, in a calibrated open area test site. Details of the test arrangement are described:

A standard Rittal enclosure was used having dimensions 1900mm (high)  $\times$  600mm (wide)  $\times$  500mm (deep). Two ventilation grilles, both 200mm square, were provided on the upper and lower faces of the door.

The drive was mounted onto the 'Standard' RFI input filter (4200-6122), which was fitted to the internal back-plate of the enclosure, the filter casing making electrical contact with the back-plate by the fixing screws. Standard unscreened power cables were used to connect the complete unit to the supply.

A standard 0.37kW AC induction motor was connected by 2.5m of shielded cable (steel braided - type SY) and mounted externally.

The motor cable screen was clamped to the enclosure back-plate. The motor cable screen was also bonded to the motor frame.

The motor cable was interrupted by a DIN rail terminal block mounted in the enclosure and the shield pigtails (50mm long) were bonded to the back plate through an earthed DIN rail terminal block.

In addition, the motor cable screen was bonded to the back-plate on both sides of the DIN rail using metal clamps.

A 2m screened control cable was connected to the drive control terminals with the screen clamped to the enclosure back-plate

A 2m unscreened status relay cable was connected to the drive.

A 2m screened communications cable was connected to the drive. The screen was not electrically connected to the drive or cubicle back panel.

The drive was operated at 6Hz, with a switching frequency of 12kHz which is the worst case for RF

emission.

No additional EMC preventative measures were taken, e.g. RFI gaskets around the cubicle doors.

The following tables summarise the results for radiated emission, showing the six highest measurements over the frequency range 30 to 1000 MHz:

Note that the emissions are similar when using the 'Low Earth Leakage' filter (4200-6123).

Frequency MHz	Emission dB $\mu$ V/m	Level required by industrial standard EN61000-6-4 at 10m
30.04	34.24	40
30.02	33.85	40
30.85	33.53	40
31.05	33.30	40
31.30	33.22	40
31.55	33.22	40

The results show that the limit for the industrial emission standard is met with a margin of at least 5dB. The limit for EN 61800-3 (IEC 61800-3) is met for the first environment with restricted distribution.

### Enclosure construction

For many installations, an enclosure will have a back-plate which will be used to mount variable speed drive modules, RFI filters and ancillary equipment. The motor cable should be bonded to the back-plate close to the drive before it leaves the enclosure wall (refer to wiring guidelines in Figure 1). However, there is no disadvantage if the motor cable is bonded at the point of exit as well, through the normal gland fixings.

Depending on construction, the enclosure wall used for cable entry may have separate panels and could make poor electrical contact at high frequencies with the remaining structure. If the motor cable is only bonded to these surfaces and not to a back-plate, then the enclosure may provide insufficient attenuation of RF emission. It is the bonding to a common metal plate which minimises radiated emission. In the tests described, opening the cubicle door had little effect on the emission level, showing that the enclosure design is not critical.

### Related product standards

The radiated emission levels specified in EN 61000-6-4 are equivalent to the levels required by the following product standards:

Radiated emission from 30 to 1000MHz		
Generic standard	Product standard	
EN 61000-6-4	CISPR 11 Class A Group 1	Industrial, scientific and medical equipment
	CISPR 11 Class A Group 1	
EN 61000-6-4	EN55022 Class A	Information technology equipment
	CISPR 22 Class A	



## WIRING GUIDELINES

The wiring guidelines on the following pages should be observed to achieve minimum emission. The details of individual installations may vary, but details which are indicated in the guidelines to be important for EMC must be adhered to closely. The guidelines do not preclude the application of more extensive measures which may be preferred by some installers. For example, the use of full 360° ground terminations on shielded cables in the place of 'pig-tail' ground connections is beneficial, but not necessary unless specifically stated in the instructions.

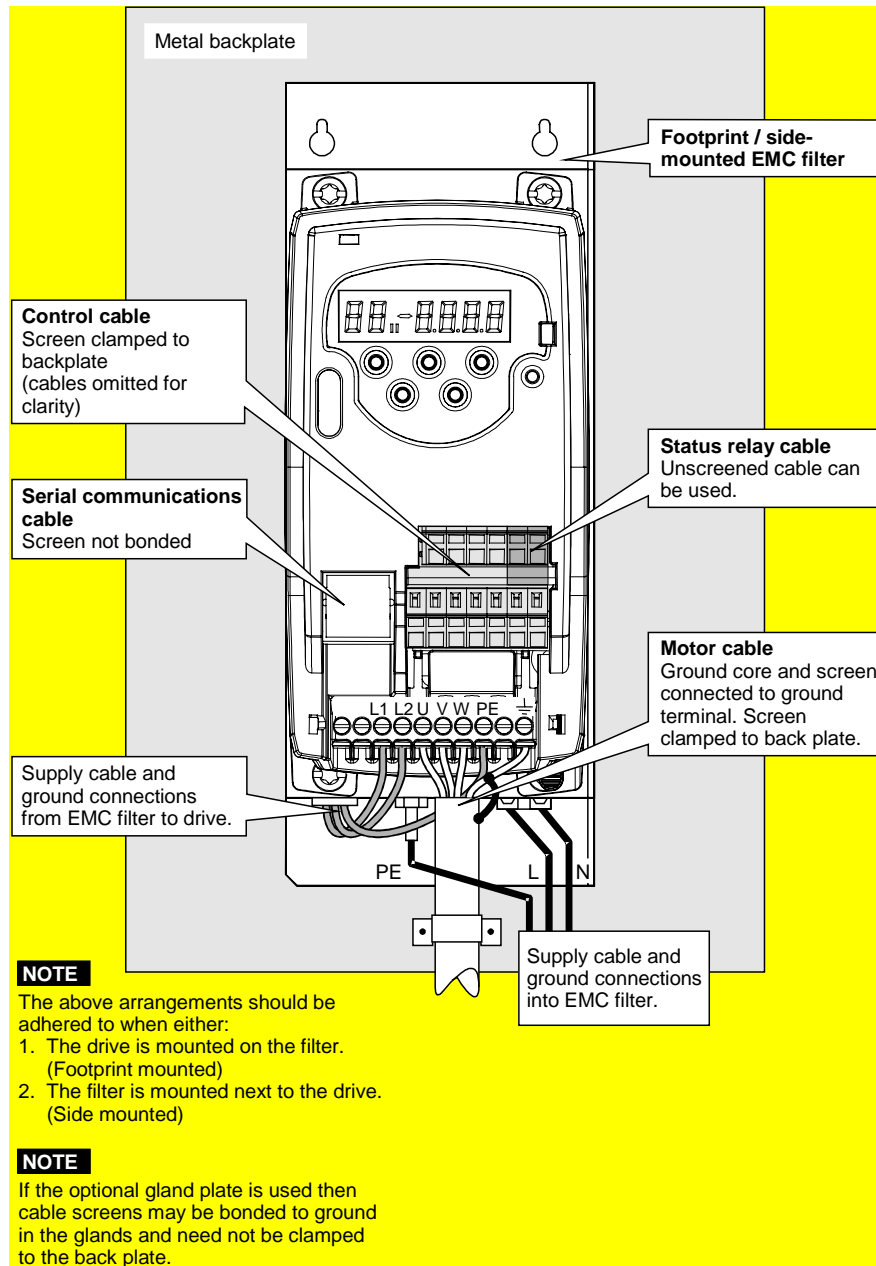


Figure 1 Wiring guidelines for SKA120025 - 1120075

1. The correct RFI filter must be fitted at the input to the drive.
2. The limits given above regarding motor cable length and drive switching frequency for the relevant filter must be adhered to.
3. Footprint filter: the drive must be correctly mounted on the filter and make good direct electrical contact with it.  
Side mounted filter: the drive and filter must be mounted together on a metal back-plate and make good electrical contact with it.
4. The filter must be connected to the drive using the wires provided. The wires must not be extended in any way.
5. The mounting surface of the filter must make good direct electrical contact with the enclosure back-plate. Any paint or other non-conducting surface must be removed.
6. A shielded (screened) or steel wire armoured cable must be used to connect the drive to motor. The shield must be connected to the enclosure back-plate by a good high-frequency connection, for example by direct clamping using a “Ω” clamp or similar.
7. Connect the shield of the motor cable to the ground terminal of the motor frame using a link that is as short as possible and not exceeding 50mm (2 in) in length. A full 360° termination of the shield to the motor terminal housing (if metal) is beneficial.
8. Ensure that the cables carrying the AC supply and the ground to the filter are at least 100mm (4 in) from the drive and the motor cable.
9. Avoid locating sensitive signal circuits in a zone extending 0.3m (12 in) all around the drive.
10. If the control circuit 0V is to be grounded, this should preferably be done at the host controller (e.g. PLC) and not at the drive, to avoid injecting noise current into the 0V circuit.  
This requirement does not apply if the complete system has been built to a high standard for EMC, using a highly bonded earth arrangement which prevents differential earth noise voltages.

## **SPECIAL REQUIREMENTS**

### **Control wiring leaves the enclosure**

The control wiring must be carried in shielded cable (one or more cables) and the shield must be clamped to the enclosure back-plate.

### **Interruptions to the motor cable**

The motor cable should ideally be a single run of shielded cable having no interruptions. In some situations it may be necessary to interrupt the cable, for example to connect the motor cable to a terminal block within the drive enclosure, or to fit an isolator switch to allow safe working on the motor. In these cases the following guidelines should be observed.

#### **– Terminal block within enclosure**

The motor cable shields should be bonded to the back-plate using uninsulated cable-clamps which should be positioned as close as possible to the terminal block. Keep the length of power conductors to a minimum and ensure that all sensitive equipment and circuits are at least 0.3m (12in) away from the terminal block. See Figure 2.

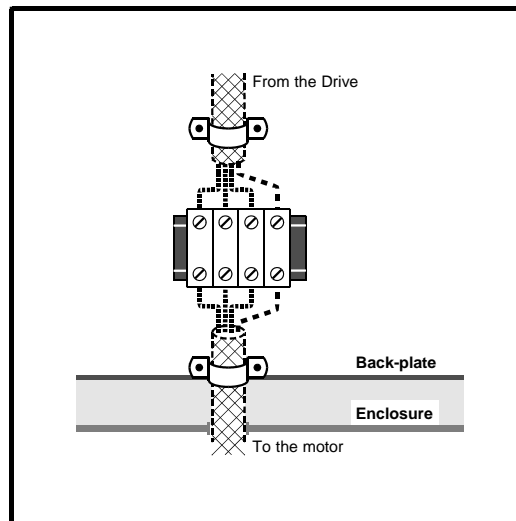


Figure 2

**Arrangement for terminal block in motor cable**

– **Using a motor isolator switch**

The motor cable shields should be connected by a very short conductor having a low inductance. The use of a flat metal bar is recommended; conventional wire is not suitable. The shields should be bonded directly to the coupling bar using uninsulated metal cable-clamps. Keep the length of the power conductors to a minimum and ensure that all sensitive equipment and circuits are at least 0.3m (12in) away. The coupling bar may be grounded to a known low impedance ground nearby, for example a large metallic structure which is connected closely to the Drive ground. See Figure 3.

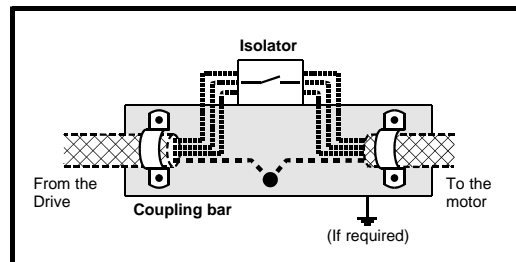


Figure 3

**Arrangement for isolator switch in motor cable**

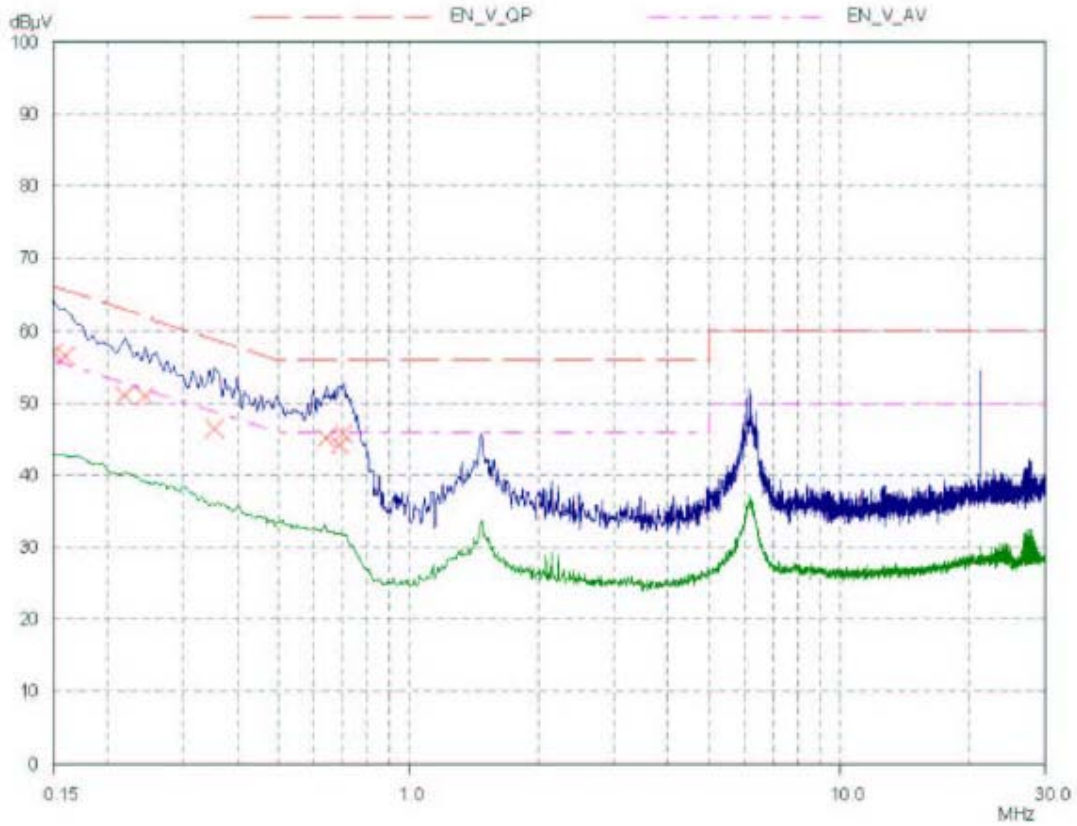


Figure 4 Conducted emission plot: 20m cable 3kHz switching using filter 4200-6122

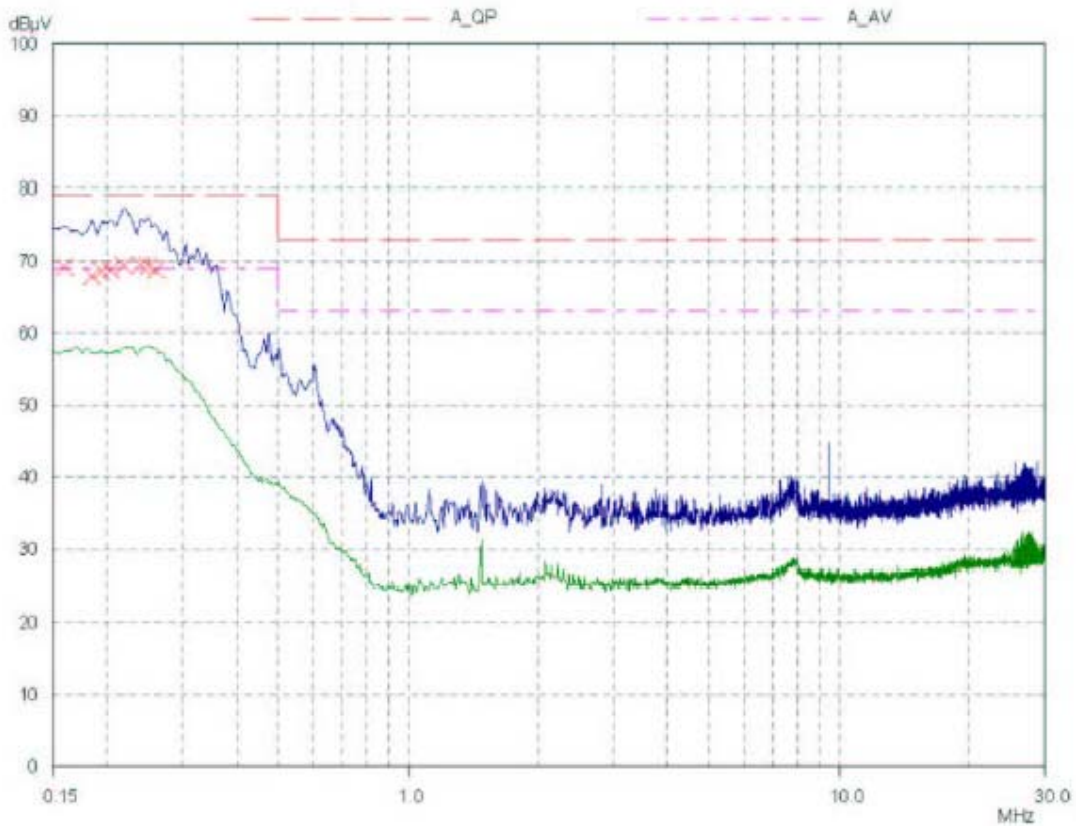


Figure 5 Conducted emission plot: 100m cable 3kHz switching using filter 4200-6122